

ImageTech

DPA-DenseBiasNet: Semi-supervised 3D Fine Renal Artery Segmentation with Dense Biased Network and Deep Priori Anatomy



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INTRODUCTION

*****Task definition

Achieving 3D renal artery tree on abdominal CTA image that reaches the

*****Deep priori anatomy based semi-supervised learning

Advantages

Adapts to more anatomical structures

end of interlobar arteries.

Clinical significance

Clinicians locate the blood feeding region corresponding to each interlobar artery easily via this fine renal artery segmentation which is important for the diagnosis and pre-operative planning of kidney disease.

*Challengings

1) Large intra-scale changes 3) Thin structure

5) Limitation of labeled data



Patient 1 Patient 2



2) Large inter-anatomy variation

4) Small volume ratio

► Focuses on both local and global anatomical information

>Improves the network's generalization ability

Suitable for thin structures

•DPA for semi-supervised anatomical adaptation

 \triangleright A convolutional denoising autoencoder was trained with numerous unlabeled data, and then its encoder part was frozen and used to extract anatomical features(Fig. 2(b))



*****Dataset

>Abdominal contrast-enhanced CT images of 170 patients who underwent LPN surgery were included in this study. The pixel size of these CT images is between 0.59mm^2 to 0.74mm^2 . The slice thickness and the spacing in zdirection were fixed at 0.75mm and 0.5mm respectively. The kidney region

of interest which size was $152 \times 152 \times Z$ was extracted.

*****Visual superiority

Ground Truth 3D U-Net ASDNet DenseBiasNet Proposed V-Net SemiFCN Ees FOA Contraction of the second

b)Large inter-anatomy variation c) Small volume ratio & Thin structure a)Large intra-scale changes Fig.1 The challenges of 3D fine renal artery segmentation.

METHODOLOGY

*****Dense biased network for fine segmentation

Advantages

Simplify the training process

Adapt to large intra-scale changes

Dense biased connection

 \succ Each layer gets a part of feature maps from all preceding layers as additional inputs and transmits a part of its output feature maps to all forward layers, as is shown in Fig.2(d).

 $\succ F_l = H_l(F_{l-1} \circ F_{l-2}[0 : k_{l-2}] \circ \dots \circ F_0[0 : k_0])$

DenseBiasNet

 \triangleright As shown in Fig.2(a), It comprises of 14 3D convolution layers, 3 maxpooling layers, 3 3D deconvolution layers used to change scales and a $1 \times 1 \times 1$ convolution layer followed a softmax as the output layer to reduce the number of channels to classes. The dense biased connection is used throughout the network to adapts to different scale arteries.



Fig.3 The visual superiority of our framework. *****Evaluation metrics advantages

Tab.1 The advantages of our method(DPA-DenseBiasNet) on each metrics.

Network	Dice	MCD	MSD
V-Net[8]	0.787(0.113)	2.872(2.196)	2.213(2.155)
3D U-Net[4]	0.750(0.162)	5.070(4.949)	4.385(4.208)
(semi)SemiFCN[3]	0.388(0.259)	8.772(10.085)	7.921(10.593)
(semi)ASDNet[9]	0.555(0.191)	8.557(5.124)	7.484(5.132)
DenseBiasNet	0.851(0.110)	2.478(2.090)	1.920(2.354)
(semi)Proposed	0.861(0.095)	1.976(1.394)	1.472(1.738)

*****Training process improvement





Fig.2 The framework of DPA-DenseBiasNet.

Test los mmmmmm 0.9975 0.015 0.9970 0.010 Higher accuracy Faster convergence speed 0.9965 0.005 Epoch Epoch Fig.4 The improvement of the training process by the dense biased connection.

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